Non-bonded interactions speeding up the number-crunching

Marcus Elstner and Tomáš Kubař

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Non-bonded interactions – why care?

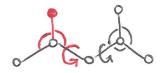
- key to understand biomolecular structure and function
 - binding of a ligand
 - efficiency of a reaction
 - color of a chromophore
- two-body potentials \rightarrow computational effort of $\mathcal{O}(N^2)$
 - good target of optimization
- solvent (H_2O) crucial role, huge amount
 - efficient description needed

How many pair-wise interactions are there?

imagine we introduce an additional atom into a system that already has N-1 atoms

bonded interactions

- we add at most (roughly)
 2 bonds, 2 angles, 3 dihedrals
- for N atoms, this is at most 7N
 − proportional to N: O(N)

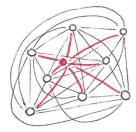


How many pair-wise interactions are there?

imagine we introduce an additional atom into a system that already has N-1 atoms

non-bonded interactions

- between the new atom and each of the previous atoms: N - 1 interactions!
- for N atoms, this is N(N − 1)/2
 proportional to N²: O(N²)



How many pair-wise interactions are there?

- Let us assume: the calculation of every atom-atom interaction takes the same amount of time
- Then, the $\mathcal{O}(N^2)$ evaluation of non-bonded interactions will be the most computationally intensive procedure in the entire simulation (the bottle neck)

Coulomb's law

elstat. interaction energy of point charges q and Q on distance r:

$$E^{\mathsf{el}} = \frac{1}{4\pi\varepsilon_0} \cdot \frac{q\cdot Q}{r}$$

electrostatic potential (ESP) induced at \vec{r} by Q at $\vec{r_1}$:

$$\phi(\vec{r}) = \frac{1}{4\pi\varepsilon_0} \cdot \frac{Q}{|\vec{r} - \vec{r_1}|}$$

ESP induced by a number of point charges Q_i :

$$\Phi(\vec{r}) = \frac{1}{4\pi\varepsilon_0}\sum_i \frac{Q_i}{|\vec{r} - \vec{r_i}|}$$

if we know ESP at \vec{r} , and q is placed there, elstat. energy follows as

$$E^{\rm el}(\vec{r}) = \Phi(\vec{r}) \cdot q$$

 \rightarrow 'electrostatic potential energy surface'

Coulomb's law

- continuous charge distribution charge density $\rho = \partial Q / \partial V$
- charge in a volume element V_i : $Q_i = \rho(\vec{r_i}) \cdot V_i = \rho(\vec{r_i}) \cdot \Delta V$
- summing the potential induced by all elements gives

$$\Phi(\vec{r}) = \frac{1}{4\pi\varepsilon_0} \sum_i \frac{\rho(\vec{r}_i) \cdot \Delta V}{|\vec{r} - \vec{r}_i|}$$

• for infinitesimal volume elements (with $d^3 \vec{r} = dV$):

$$\Phi(\vec{r}) = \frac{1}{4\pi\varepsilon_0} \int \frac{\rho(\vec{r_1})}{|\vec{r} - \vec{r_1}|} \,\mathrm{d}^3\vec{r_1}$$

• elstat. energy of a charge density $\rho(\vec{r})$ follows as

$$E = \frac{1}{2} \int \Phi(\vec{r}) \cdot \rho(\vec{r}) \,\mathrm{d}V = \frac{1}{8\pi\varepsilon_0} \iint \frac{\rho(\vec{r}_1) \cdot \rho(\vec{r})}{|\vec{r} - \vec{r}_1|} \,\mathrm{d}^3\vec{r} \,\mathrm{d}^3\vec{r}_1$$

Intro to electrostatic interaction

Poisson's equation

- needs to be solved to get ESP from charge distribution (differential equation for Φ as a function of \vec{r}):

$$abla^2 \Phi(\vec{r}) = -rac{
ho(\vec{r})}{arepsilon}$$

– if permittivity ε is not constant:

$$\nabla\left(\varepsilon\nabla\Phi(\vec{r})\right) = -\rho(\vec{r})$$

example: ESP of Gaussian charge density around \vec{o} with width σ :

$$\rho(r) = Q \cdot \frac{1}{\sigma^3 \sqrt{2\pi^3}} \cdot \exp\left[\frac{r^2}{2\sigma^2}\right]$$

solution of Poisson's equation:

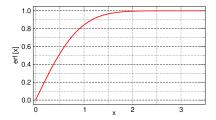
$$\Phi(r) = rac{1}{4\piarepsilon} \cdot rac{Q}{r} \cdot ext{erf} \left[rac{r}{\sqrt{2}\sigma}
ight]$$

Intro to electrostatic interaction

Poisson's equation

solution for Gaussian charge density:

$$\Phi(r) = rac{1}{4\piarepsilon} \cdot rac{Q}{r} \cdot ext{erf} \left[rac{r}{\sqrt{2}\sigma}
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Intro to electrostatic interaction

Poisson's equation

solution for Gaussian charge density:

$$\Phi(r) = rac{1}{4\piarepsilon} \cdot rac{Q}{r} \cdot ext{erf}\left[rac{r}{\sqrt{2}\sigma}
ight]$$

if we move far from the center of charge density (r is large)
■ erf converges to 1, ESP equals that of a point charge placed in o

 accordance with experience – a point charge and a well-localized charge density interact with distant charges in the same way

• actually, we need not go far to see that

$$- \operatorname{erf} = 0.999$$
 already for $x = 2.4\sigma$

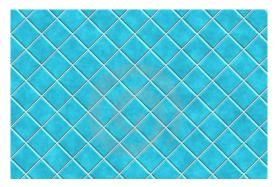
Biomolecule in solution

typical MD simulations – molecular system in aqueous solution task – make the system as small as possible (reduce cost) straightforward solution – single molecule of solute (protein, DNA) with a smallest possible number of H₂O molecules typical – several thousand H₂O molecules in a cube $n \times n \times n$ nm

issue – everything is close to the surface,
while we are interested in a molecule in bulk solvent
so – we may be simulating something else than what we want

Periodic boundary conditions

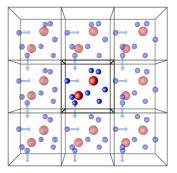
- elegant way to avoid these problems
- molecular system placed in a regular-shaped box
- the box is virtually replicated in all spatial directions



Periodic boundary conditions

- elegant way to avoid these problems
- molecular system placed in a regular-shaped box
- the box is virtually replicated in all spatial directions
- positions (and velocities) of all particles are identical in all replicas, so we can keep only one copy in the memory
- this way, the system is infinite no surface!
- the atoms near the wall of the simulation cell interact with the atoms in the neighboring replica

PBC – example



isaacs.sourceforge.net

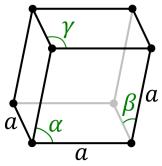
PBC – features

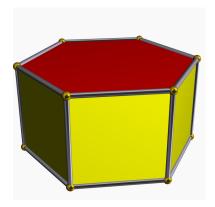
- small problem artificial periodicity in the system (entropy ③)
 still much better than boundary with vacuum
- only coordinates of the unit cell are recorded
- atom that leaves the box enters it on the other side.
- carefull accounting of the interactions of atoms necessary! simplest – minimum image convention:
 - an atom interacts with the nearest copy of every other
 - interaction with two different images of another atom, or even with another image of itself is avoided

PBC – box shape

may be simple – cubic or orthorhombic, parallelepiped (specially, rhombohedron), or hexagonal prism

$$\alpha = \beta = \gamma \neq 90^{\circ}$$

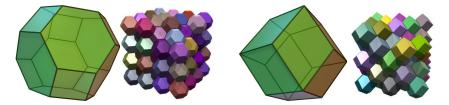




PBC – box shape

... but also more complicated

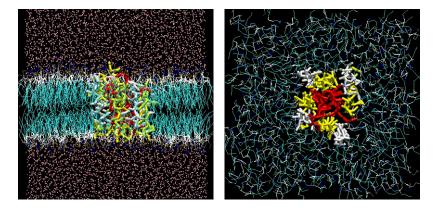
- truncated octahedral or rhombic dodecahedral
- quite complex equations for interactions & eqns of motion



advantage for simulation of spherical objects (globular proteins) – no corners far from the molecule filled with unnecessary H_2O

PBC – box shape

2D objects – phase interfaces, membrane systems – usually treated in a slab geometry



Cut-off - simple idea

non-bonded terms – bottleneck of the calculation with PBC – infinite number of interaction pairs in principle, still too many interaction with min. image convention but the interaction gets weaker with distance

simplest and crudest approach to limit the number of calculations: neglect interaction of atoms further apart than r_c – cut-off

very good for rapidly decaying LJ interaction $(1/r^6)$ $(r_c = 10 \text{ Å})$ not so good for slowly decaying electrostatics (1/r)

 sudden jump (discontinuity) of potential energy, disaster for forces at the cut-off distance

Cut-off - better: shift

shift the whole function by $V(r_c)$ – eliminate the jump at r_c :

$$V^{\mathsf{sh}}(r) = egin{cases} V(r) - V(r_c), & ext{for} \quad r \leq r_c, \ 0, & ext{otherwise}. \end{cases}$$

still, the gradients (forces) are at r_c discontinuous!

shift-force potential gets rid of that $(V' \equiv dV/dr)$:

$$V^{\mathrm{sf}}(r) = egin{cases} V(r) - V(r_c) - V'(r_c) \cdot (r - r_c), & ext{for} \quad r \leq r_c, \ 0, & ext{otherwise}. \end{cases}$$

drawback - the Coulomb energy is not quite Coulomb anymore

Cut-off - better: reaction field

reaction field interaction:

assume a constant dielectric environment beyond the cut-off r_c , with a dielectric constant ε_{rf} (parameter):

$$V^{\rm rf}(r) = \frac{1}{r} \cdot \left(1 + \frac{\varepsilon_{\rm rf} - 1}{2\varepsilon_{\rm rf} + 1} \cdot \frac{r^3}{r_c^3}\right) - V^{\rm rf}(r_c)$$

$$F^{\rm rf}(r) = -\frac{1}{r^2} \cdot \left(1 - \frac{2\varepsilon_{\rm rf} - 2}{2\varepsilon_{\rm rf} + 1} \cdot \frac{r^3}{r_c^3}\right)$$

(the force at cut-off is very small, and vanishes with ε_{rf}) there is a physical motivation – possible advantage

Cut-off – better: switch

switch off the Coulomb interaction from full strength to zero, starting from a certain distance r_1 , by multiplication with a function passing from 1 to 0

$$V^{\text{sw}}(r) = \begin{cases} V(r) & \text{for } r < r_1, \\ V(r) \cdot \varphi\left(\frac{r-r_1}{r_c - r_1}\right) & \text{for } r_1 < r < r_c, \\ 0, & \text{otherwise.} \end{cases}$$

- interaction altered in the cut-off region

switch-force: $F^{\text{fsw}}(r) = F(r) \cdot \varphi\left(\frac{r-r_1}{r_c-r_1}\right)$ for $r_1 < r < r_c$, if needed, obtain energy formally as $V^{\text{fsw}}(r) = \int_{\infty}^{r} F^{\text{fsw}}(r')$

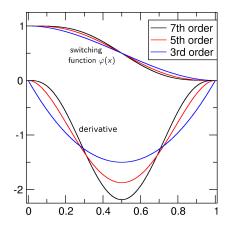
Note: switching function

a general concept to approximation avoiding abrupt change of a value of the function

$$f_{sw}(x) = f(x) \cdot \varphi\left(\frac{x - x_1}{x_0 - x_1}\right)$$

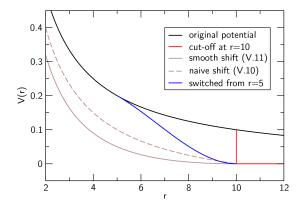
switching function $\varphi(x)$

- defined on interval (0, 1)
- goes from 1 to 0
- need continuous derivative?
 cubic function
- need cont. 2nd derivative?
 - 5th-order polynom



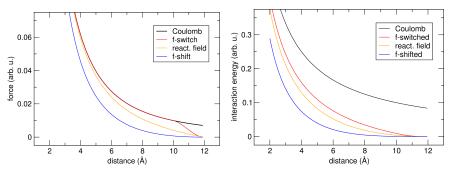
Cut-off – better alternatives

elstat. interaction energy of two unit positive charges



shift / switch – applied here to energy, better apply them to force

Cut-off – better alternatives



Neighbor lists

cut-off – we still have to calculate the distance for every two atoms (to compare it with the cut-off distance)

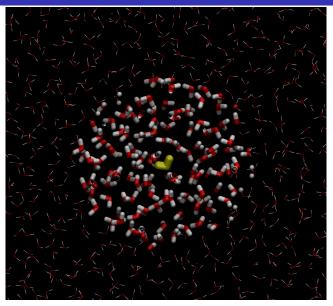
 \rightarrow we do not win much yet – there are still $\mathcal{O}(N^2)$ distances

observation: pick an atom A.

the atoms that are within cut-off distance r_c around A, remain within r_c for several consecutive steps of dynamics, while no other atoms approach A that close

idea: maybe it is only necessary to calculate the interactions between A and these close atoms – neighbors

Neighbor lists



Neighbor lists

what will we do?

calculate the distances for every pair of atoms less frequently, i.e. every 10 or 20 steps of dynamics, and record the atoms within cut-off distance in a neighbor list

atom	how many?	list of neigboring atoms											
1	378	2191	408	1114	1802	262	872	649	805	1896	2683	114	189
2	403	1788	1624	1048	1745	2546	506	203	288	2618	1445	880	133
3	385	779	2869	800	2246	1252	570	454	1615	1656	1912	2395	152
4	399	367	2143	1392	1448	1460	1411	2921	2725	429	845	2601	181
5	406	1385	425	1178	2112	1689	1897	1650	1747	1028	1366	605	176
6	388	1748	130	2244	631	1677	1748	2566	303	552	562	1142	255
7	379	20	15	1322	196	1590	655	552	1401	2177	411	2904	236
8	395	888	1074	786	2132	1703	218	1846	337	1683	1917	2005	94
9	396	2433	934	1055	1518	2750	2534	1697	2006	769	2407	1478	123
10	381	2461	1910	459	2628	2523	1709	2069	1151	1710	2107	1909	13
11	400	1029	756	670	1592	612	676	1473	2859	202	986	155	26¢

then – calculate the interaction for each atom only with for the atoms in the neighbor list – formally $\mathcal{O}(N)$ note – the build of the neighbor list itself is $\mathcal{O}(N^2)$, which can be reduced with further tricks ('cell lists')

Accounting of all of the replicas

cut-off – often bad approximation, e.g. with highly charged molecular systems (DNA, some proteins) artificial forces with switching function \rightarrow e.g. artificial accumulation of ions around cut-off

only way – abandon the minimum image convention and cut-off – sum up the long-range Coulomb interaction between all the replicas of the simulation cell

introduce \vec{n} running over all the replicas

- for $|\vec{n}| = 0$, we have $\vec{n} = (0, 0, 0)$ the central unit cell.
- for $|\vec{n}| = L$: $\vec{n} = (0, 0, \pm L)$, $\vec{n} = (0, \pm L, 0)$, $\vec{n} = (\pm L, 0, 0)$ - the six neighboring unit cells.

• continue with $|\vec{n}| = \sqrt{2}L$: 12 cells touching with edge...

Can we sum it up simply?

sum of Coulomb interactions over all replicas:

$$E^{\mathsf{Coul}} = rac{1}{2} \sum_{i,j} \sum_{\mathsf{replicas}\ ec{n}} rac{q_i \cdot q_j}{|ec{r_{ij}} + ec{n}|}$$

i and *j* run over all atoms in the unit cell (r_{ij} - their distance) infinite sum with special convergence problems alternating harmonic series $\sum_{n}(-1)^{n}/n$ - conditionally convergent: it converges $\sum_{i=1}^{\infty} a_{i} < \infty$, but does not converge absolutely: $\sum_{i=1}^{\infty} |a_{i}| = \infty$ - convergence is slow and dependent on the order of summation Non-bonded interactions

Complete treatment of non-bonded interactions

BTW: conditionally convergent series

$$I: S = 1 - \frac{1}{2} + \frac{1}{3} - \frac{1}{4} + \frac{1}{5} - \frac{1}{6} + \frac{1}{7} - \frac{1}{8} + \dots$$

$$II: \frac{1}{2}S = +\frac{1}{2} - \frac{1}{4} + \frac{1}{6} - \frac{1}{8} + \dots$$

$$I + II: \frac{3}{2}S = 1 + \frac{1}{3} - \frac{1}{2} + \frac{1}{5} + \frac{1}{7} - \frac{1}{4} + \frac{1}{9} + \dots$$

$$= 1 - \frac{1}{2} + \frac{1}{3} - \frac{1}{4} + \frac{1}{5} - \frac{1}{6} + \dots = S \quad (sic!)$$

Sum it up not so simply – Ewald

any smart way to calculate ESP induced by all images of all atoms?

$$\Phi(ec{r_i}) = \sum_j \sum_{ ext{replicas} |ec{n}|} rac{q_j}{|ec{r_{ij}} + ec{n}|}$$

idea: pass to a sum of two series that will converge rapidly:

$$\sum \frac{1}{r} = \sum \frac{f(r)}{r} + \sum \frac{1 - f(r)}{r}$$

may seem awkward, but will work well ©

how can we implement this idea?

Sum it up not so simply – Ewald

summing over point charges – difficult (convergence problem) Ewald method uses Gaussian densities of the same magnitude:

$$q_j
ightarrow q_j \cdot \left(rac{lpha}{\sqrt{\pi}}
ight)^3 \exp\left[-lpha^2 \cdot |ec{r_j}|^2
ight]$$

ESP for a Gaussian charge density:

$$\Phi(\vec{r}) = q_j \cdot \frac{\operatorname{erf}\left[\alpha \cdot r\right]}{r}$$

erf: "error function"

$$\operatorname{erf}[x] = \frac{2}{\sqrt{\pi}} \int_0^x \exp[-t^2] dt \qquad \operatorname{erfc}[x] = 1 - \operatorname{erf}[x]$$

Sum it up not so simply – Ewald

with Ewald: summing ESP induced by all charges, we obtain

$$\Phi(\vec{r_i}) = \sum_j \sum_{\text{replicas } |\vec{n}|} q_j \cdot \frac{\text{erf} \left[\alpha \cdot |\vec{r_{ij}} + \vec{n}|\right]}{|\vec{r_{ij}} + \vec{n}|} \rightarrow \sum \frac{f(r)}{r}$$

do not forget: we have to add a correction – difference of potentials induced by Gaussians and by point charges

$$\rightarrow \sum \frac{1-f(r)}{r}$$

Sum it up not so simply – Ewald

the full ESP induced by all replicas of all charges:

$$\begin{aligned} \Phi(\vec{r_i}) &= \sum_{j} \sum_{\text{replicas} |\vec{n}|} q_j \cdot \frac{\text{erfc} \left[\alpha \cdot |\vec{r_{ij}} + \vec{n}|\right]}{|\vec{r_{ij}} + \vec{n}|} \\ &+ \sum_{j} \sum_{\text{replicas} |\vec{n}|} q_j \cdot \frac{\text{erf} \left[\alpha \cdot |\vec{r_{ij}} + \vec{n}|\right]}{|\vec{r_{ij}} + \vec{n}|} \\ &= \Phi^{\text{real}}(\vec{r_i}) + \Phi^{\text{rec}}(\vec{r_i}) \end{aligned}$$

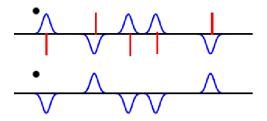
 $\Phi^{\text{real}}(\vec{r_i})$ – real-space contribution

- from a certain, quite small distance (depending on α): point charges and the charge densities cancel each other - this contribution vanishes and we can use cut-off here

Ewald – two contributions

real-space contribution to the Ewald sum

 original point charges (red) and Gaussian charge densities (blue) of the same magnitude but opposite sign

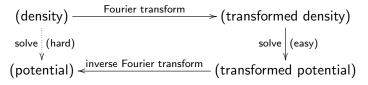


 a distant Gaussian 'looks much like' a point charge, and the difference of ESP goes to zero – cut-off is justified

Ewald – 2nd contribution

reciprocal-space contribution:

the total charge density is periodic \rightarrow it may be meaningful to Fourier-transform the calculation to the reciprocal space



$$\hat{f}(\xi) = \int_{-\infty}^{\infty} f(x) \cdot \exp[-2\pi i \cdot x \cdot \xi] dx$$

Re $\hat{f}(\xi) = \int_{-\infty}^{\infty} f(x) \cdot \cos[x \cdot \xi] dx$
Im $\hat{f}(\xi) = \int_{-\infty}^{\infty} f(x) \cdot \sin[x \cdot \xi] dx$

Ewald – 2nd contribution

 $\Phi^{\text{rec}}(\vec{r_i})$ – reciprocal-space contribution

- with 'reciprocal' vector $\vec{k} = \left(k_x \cdot \frac{2\pi}{L_x}, k_y \cdot \frac{2\pi}{L_y}, k_z \cdot \frac{2\pi}{L_z}\right)$, $k_i \in \mathcal{Z}$
- best evaluated in the form

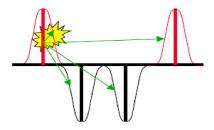
$$\Phi^{\text{rec}}(\vec{r_i}) = \frac{4\pi}{V} \cdot \sum_{\vec{k} \neq \vec{o}} \frac{1}{\vec{k}^2} \cdot \exp\left[-\frac{|\vec{k}|^2}{4\alpha^2}\right] \cdot \sum_j q_j \cdot \exp[-i \cdot \vec{k} \cdot \vec{r_{ij}}]$$

- terms decrease with increasing $|\vec{k}|$ quickly cut-off possible
- converges fast with large Gaussian width lpha
- the value of α is a compromise between the requirements of real- and reciprocal-space calculations

both contributions – favorable convergence behavior \rightarrow we can evaluate electrostatic interactions with atoms in all periodic images

Ewald – the last contribution

broadened charge density interacts with itself and this energy must be subtracted from the final result



Coulomb self-energy of a broadened Gaussian:

$$E^{\mathsf{self}} = \sum_j q_j \cdot \Phi(ec{o}) = \sum_j q_j \cdot q_j \cdot rac{lpha}{\sqrt{\pi}}$$

Ewald - complete expression for energy

- 3 contributions:
 - 'real-space'

$$E^{\mathsf{real}} = rac{1}{2} \sum_{j} q_{j} \cdot \Phi^{\mathsf{real}}(\vec{r_{j}})$$

'reciprocal-space'

$$E^{\mathsf{rec}} = rac{1}{2} \sum_{j} q_{j} \cdot \Phi^{\mathsf{rec}}(ec{r_{j}})$$

'self-energy'

$$E^{\mathsf{Ewald}} = E^{\mathsf{real}} + E^{\mathsf{rec}} - E^{\mathsf{self}}$$

Ewald – optional additional contribution

Surface / dipole term

• for systems with zero charge and dipole moment $ec{\mu}_{ ext{tot}}
eq ec{o}$

$$\Phi^{\rm sur}(\vec{r_i}) = \frac{4\pi}{3} \frac{\vec{r_i} \cdot \vec{\mu}_{\rm tot}}{V}$$

- this describes the situation with surrounding vacuum
- universal application may lead to problems when mobile ions cross the box boundaries (abrupt changes of \(\vec{\mu}\)tot)
- if this term is not present
 - 'tin-foil' boundary conditions surrounding $arepsilon=\infty$

Thinking about Ewald

Ewald summation – correct Coulomb interaction energy at higher computational cost (compared to cut-off):

- scales with the number of atoms as $\mathcal{O}(N^2)$
- with a better algorithm $\mathcal{O}(N^{\frac{3}{2}})$
- not efficient enough for large-scale simulations
- goal improved efficiency of the long-range sum (reciprocal-space contribution)

particle-mesh Ewald method (1993)

- combines ideas from crystallography (Ewald method) and plasma physics (particle-mesh method)
- key to success 3D fast Fourier transform technique

Long–range energy with PME

PME works with a regular grid constructed in the simulation box

step 1

convert the point charges to Gaussian charge densities and spread on the grid in the form of splines practically, we need to have charges discretized on the grid points if an atom is close to the edge of the box, a part of its charge must be put to the opposite side of the box (PBC)

Long-range energy with PME

step 2

Fourier transform the charge density on the grid

- discrete 3D fast Fourier transform technique

solve Poisson's eqn in the reciprocal space

 \rightarrow energy and Fourier transform of potential

$$E^{\mathsf{rec}} = \frac{1}{2} \sum_{k_1=0}^{K_1-1} \sum_{k_2=0}^{K_2-1} \sum_{k_3=0}^{K_3-1} Q(k_1, k_2, k_3) \cdot (\Theta^{\mathsf{rec}} \star Q)(k_1, k_2, k_3)$$

3D-FFT used to calculate the convolution $\Theta^{\text{rec}} \star Q$ – this corresponds to the ESP in reciprocal space Θ^{rec} depends on box size and character of splines

Long-range energy with PME

step 3

get the potential in real space (inverse Fourier transform), interpolate its derivative to calculate the forces

- expressed in terms of splines - analytical calculation

step 4

get E^{real} and E^{self} – directly from the presented expressions

step 5

attention – the reciprocal energy/forces include contributions from atom pairs that are connected with bonds

- these have to be subtracted afterwards (excluded)

$$E_{ ext{excl}}^{ ext{rec}} = -\sum_{i,j}^{ ext{list}} rac{1}{4\piarepsilon_0} rac{q_i\cdot q_j}{r_{ij}} ext{ erf } [lpha\cdot r_{ij}]$$

Long-range energy with PME

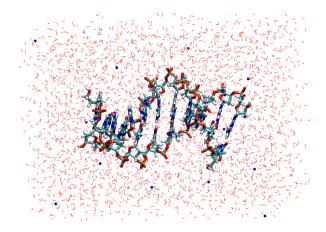
PME parameters: spacing of grid ca. 1 Å, $\alpha^{-1} \approx 2.5 \text{ Å} \rightarrow \text{short-range cutoff} \leq 10 \text{ Å possible}$

neighbor lists used for the real-space interactions \rightarrow linear scaling of real-space calculation ($\mathcal{O}(N)$)

complexity of the long-range PME component: $O(N \cdot \log N)$ due to the efficiency of FFT modern implementations – nearly as efficient as cut-off!

Water in biomolecular simulations

most simulations – something in aqueous solutions H_2O – usually (many) thousands molecules



Water in biomolecular simulations

most simulations – something in aqueous solutions H_2O – usually (many) thousands molecules

example - simulation of DNA decanucleotide:

- PBC box $3.9 \times 4.1 \times 5.6$ nm (smallest meaningful)
- 630 atoms in DNA, 8346 atoms in water and 18 Na⁺
- concentration of DNA: 18 mmol/L very high!
- of all pair interactions: 86 % are water-water, most of the others involve water

Water models

most interactions involve H_2O

→ necessary to pay attention to its description model of water must be simple enough (computational cost) and accurate enough, at the same time

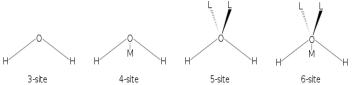
water models - usually rigid

bond lengths and angles do not vary – constraints

molecule with three sites (atoms in this case), or up to six sites

- three atoms and virtual sites corresponding

to a 'center' of electron density or lone electron pairs



Water models

- TIP3P (very similar is SPC)
 - most frequently used
 - 3 atoms with 3 rigid bonds, charge on every atom (-0.834/+0.417)

only the O possesses non-zero LJ parameters (optimization)
 TIP4P

- negative charge placed on virtual site M rather than on the O
- electric field around the molecule described better

TIP5P

- 2 virtual sites L with negative charges near the O lone pairs
- better description of directionality of H-bonding etc. (radial distribution function, temperature of highest density)

Water models

SSD 2. SPC 2. SPC/E 2.	2.27 ^[181] 2.35 ^[3] 2.39 ^[994]	constant 72 [511] 65 [185]	self-diffusion, 10 ⁻⁵ cm ² /s 2.13 ^[511] 3.85 ^[182] 2.49 ^[182]	Average configurational energy, kJ mol ⁻¹ -40.2 ^[511] -41.0 ^[185]	Density maximum, °C -13 ^[511] -45 ^[983]	Expansion coefficient, 10 ⁻⁴ °C ⁻¹
SPC 2. SPC/E 2.	2.27 ^[181] 2.35 ^[3] 2.39 ^[994]	65 ^[185] 71 ^[3]	3.85 [182]			-
SPC/E 2.	2.35 ^[3] 2.39 ^[994]	71 [3]		-41.0 [185]	AE [983]	
SPC/E 2.	2.39 ^[994]	71 ^[3] 79 63 ^[994]	2.49 [182]			7.3 [704] **
SBC/Ew		79.63 [994]		-41.5 [3]	-38 [183]	5.14 [994]
SFC/FW Z	2.52 [3]		2.32 [994]	-	-	4.98 [994]
		77 [3]	2.6 [3]	-43.2 [3]	+4 [184]	-
TIP3P 2.	2.35 [180]	82 [3]	5.19 ^[182]	-41.1 [180]	-91 [983]	9.2 [180]
		193 ^[994]	3.53 [994]	-	-	7.81 [994]
	2.78 [2031]	80.7 [2031]	2.54 [2031]	-	4 [2031]	2.5 [2031]
	1.85 [1251]	-	1.5 [1251]	-42.7 [1251]	+10 [1251]	3.5 [1251]
		53 ^{a [3]}	3.29 [182]	-41.8 [180]	-25 [180]	4.4 [180]
TIP4P-Ew 2.	2.32 [649]	62.9 ^[649]	2.4 [649]	-46.5 [649]	+1[649]	3.1 ^[649]
TIP4P-FQ 2.	2.64[197]	79 [197]	1.93 [197]	-41.4 [201]	+7 [197]	-
TIP4P/2005 2.	2.305 [984]	60 ^[984]	2.08 [984]	-	+5 [984]	2.8 ^[984]
			1.93 ^{[1765}]	-	+7 [1765]	-
OPC 2.		78.4 [2168]	2.3 [2168]	-	-1 [2168]	2.7 [2168]
			3.66 [201]	-41.7 [201]		-
		88 [704]	2.6 [704]	-41.1 [704]	-78 ^[1939]	7.0 [704]
COS/D2 2.	2.55 [1617]	78.9 [1617]	2.2 [1617]	-41.8 [1617]	-	4.9 [1617]
GCPM 2.	2.723 [859]	84.3 [859]	2.26 [859]	-44.8 [859]	-13 [859]	-
		79 [933]	2.33 [933]	-41.5 [933]	<-53 [1999]	-
BK3 2.		79 ^[2080]	2.28 [2080]	-43.32 [2080]	+4 [2080]	3.01 [2080]
		78.1 [1999]	2.14 [1999]	-41.5 ^[1999]	-48 [1999]	-
TIP5P 2.	2.29 [180]	81.5 [180]	2.62 [182]	-41.3 [180]	+4 [180]	6.3 ^[180]
		92 ^[619]	2.8 ^[619]		+8 [619]	4.9 ^[619]
	2.67 [1027]	67.2 ^[1027]	1.4 [1027]	-45.1 [1027]	-	-
		98 [256]	1.81 [256]	-41.5 [256]	+25 [256]	-
Six-site * 1.	.89 ^[491]	33 [491]	-	-	+14 [491]	2.4 [491]
Experimental 2.		78.4	2.30	-41.5 [180] at 20 °C and ** at 27 °C	+3.984	2.53

All the data is at 25 °C and 1 atm, except * at 20 °C and ** at 27 °C.

Continuum electrostatics methods

Situation up to now

- molecules in an explicit solvent
- all interactions between atoms involved
- polarizability / permittivity of the solvent
 - present in the simulation as a consequence of interactions and dynamics
- for instance, solvation free energy is involved "by the way"
 if desired, may be evaluated with special methods

Continuum electrostatics methods

Example – polypeptide in the $\alpha\text{-helix}$ and $\beta\text{-sheet}$ conformations.

The free energy difference of the two structures is given by

- the difference of internal energies / enthalpies
- the entropic contributions above all vibrational entropy
- the difference of free energies of solvation

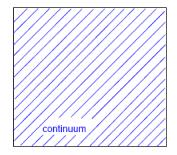
 $\alpha\text{-helix:}$ much larger dipole moment than $\beta\text{-sheet}$

- $\rightarrow \alpha$ -helix is better solvated in a polar medium (H₂O)
- \rightarrow crucial effect of solvation on the equilibrium between conformations of solvated peptide

Motivation: the amount of solvent becomes excessive easily, so it may be meaningful to abandon explicit solvent representation, and apply an implicit model instead

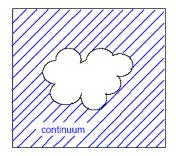
Continuum electrostatics methods

Solvation free energy: $\Delta G_{solv} = \Delta G_{cav} + \Delta G_{vdW} + \Delta G_{ele}$



Continuum electrostatics methods

Solvation free energy: $\Delta G_{solv} = \Delta G_{cav} + \Delta G_{vdW} + \Delta G_{ele}$



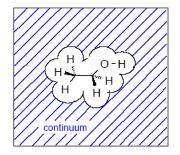
A cavity in the solvent is formed

- rearrangement of the solvent molecules

 ΔG_{cav} : decrease of S and loss of solvent-solvent interactions

Continuum electrostatics methods

Solvation free energy: $\Delta G_{solv} = \Delta G_{cav} + \Delta G_{vdW} + \Delta G_{ele}$



A cavity in the solvent is formed

- rearrangement of the solvent molecules

 ΔG_{cav} : decrease of S and loss of solvent-solvent interactions

■ solute-solvent interaction - van der Waals and electrostatic

Solvent-accessible surface area

SASA – important concept

- solvent-exposed surface of molecule as a solid body
- reasonable approx.: ΔG_{cav} and ΔG_{vdW} proportional to SASA.
- total surface composed from surfaces of individual atoms S_i

• then:
$$\Delta G_{cav} + \Delta G_{vdW} = \sum_i c_i \cdot S_i$$

 alternative: obtain SASA by rolling a ball of a certain diameter (typically 2.8 Å to mimic H₂O) on the molecular surface

Solvent-accessible surface area

When does it work?

- if the electrostatic effect of the surrounding solvent dominates (shielding of solvent-exposed charged side chains of proteins)
- not if there is specific solute-solvent interaction (like hydrogen bonding)
- Difficult example: dynamics of small peptides dissolved in water
 - competition between various hydrogen-bonding patterns

Continuum electrostatics methods

Big question: how to calculate ΔG_{ele} ?

often used is the term "reaction field"

$$\Delta G_{\rm ele} = q \cdot \Phi_{\rm rf}(\vec{r})$$

for moving the cavity with the solute from vacuo to the solvent

Born and Onsager models

Born: the work to bring charge q from vacuo into spherical cavity of radius ain solvent with dielectric constant ε :

$$\Delta G_{\mathsf{ele}} = -rac{q^2}{2a}\left(1-rac{1}{arepsilon}
ight)$$

arepsilon: 1 for vacuo (thus $\Delta G_{
m ele}=$ 0), 80 for water, 2 to 20 for protein

Onsager and Kirkwood: model for dipole μ in cavity

$$\begin{split} \Phi_{\mathsf{rf}} &=& \frac{2(\varepsilon-1)}{2\varepsilon+1} \cdot \frac{1}{a^3} \cdot \mu \\ \Delta G_{\mathsf{ele}} &=& -\frac{1}{2} \Phi_{\mathsf{rf}} \cdot \mu \end{split}$$

Born and Onsager models

simple models

- implemented in many standard programs
- quite unrealistic approximations even for small molecules

Extensions:

polarizable continuum model (PCM) –

arbitrary surfaces constructed with the use of vdW radii of individual atoms

 conductor-like screening models (COSMO) – polarization of the dielectric (insulating) solvent derived from scaled-conductor approximation.

Poisson–Boltzmann equation (PBE)

For big molecules, the simple models may be too simple and inefficient at the same time :-(

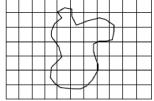
other approximations - starting from Poisson's equation

 $\nabla \varepsilon \nabla \Phi = -4\pi \rho$

given – charge distribution ρ and dielectric constant ε to be found – potential Φ

possibility to solve:

 discretize on a 3D grid, use finite differences calc. Φ on every grid point iteratively



lons in the solvent

ions are very important – counterions compensate charged solute, or salt mimicks physiologic conditions

the position of ions depends on the potential:

$$\rho_{\text{ions}} = \sum_{i} q_{i} \cdot c_{i} \cdot \exp\left[-\frac{q_{i} \cdot \Phi(r)}{k_{\text{B}}T}\right]$$

or: anions like to be where $\Phi>0,$ and cations like $\Phi<0$

an additional term appears in Poisson's equation: linearized Poisson-Boltzmann equation at low ionic strength:

$$abla arepsilon
abla
abla \Phi = -4\pi
ho + arepsilon \cdot \kappa^2 \cdot \Phi(r)$$

with the Debye–Hückel parameter $\kappa^2 = \frac{8\pi q^2 I}{\varepsilon \cdot k_{\rm B} T}$ (ionic strength $I = \frac{1}{2} \sum_i c_i z_i^2$, c_i concentration, z_i charge of ion i)

lons in the solvent – PBE

charge distribution on the protein
 polarizes the dielectric outside ("solvent")
 → screening of any solvent-exposed charges of the protein
 effectively, charges pointing into the solvent will vanish nearly
 solvent ions will distribute to make
 the overall charge distribution more uniform
 if a negative charge points into the solvent,
 a cation will be located close to it

The solvent around a protein should always be taken into account.

 $\mathsf{PBE}-\mathsf{not}$ efficient enough to be calculated in every MD step \rightarrow approximations are necessary

Generalized Born model (GB)

idea - use the simple Born equation for MM atomic charges

$$\Delta G^1_{\mathsf{ele}} = -\left(1-rac{1}{arepsilon}
ight)\sum_i rac{q_i^2}{2a_i}$$

the interaction of individual charges changes in solution

$$E_{\text{ele}} = \frac{1}{2} \sum_{i \neq j} \frac{1}{\varepsilon} \frac{q_i \cdot q_j}{r_{ij}} = \frac{1}{2} \sum_{i \neq j} \frac{q_i \cdot q_j}{r_{ij}} - \frac{1}{2} \left(1 - \frac{1}{\varepsilon} \right) \sum_{i \neq j} \frac{q_i \cdot q_j}{r_{ij}}$$

giving another contribution to solvation free energy

$$\Delta G_{\mathsf{ele}}^2 = -rac{1}{2}\left(1-rac{1}{arepsilon}
ight)\sum_{i
eq j}rac{q_i\cdot q_j}{r_{ij}}$$

solvation free energy $= \Delta \textit{G}_{ele}^1 + \Delta \textit{G}_{ele}^2$

Generalized Born model (GB)

problem 1 – Born's formula holds for interaction of charges located in spherical cavities (with radii a_i)

- only valid for charged bodies of general shapes if $r_{ij} \gg a_i + a_j$
- two extreme cases are covered:

$$E = \begin{cases} \frac{q_i^2}{a_i}, & \text{if } i = j \text{ (`self-interaction, i.e. solvation energy)} \\ \frac{a_i}{q_i \cdot q_j}, & \text{if } i \neq j \text{ and } r_{ij} \to \infty \end{cases}$$

what to do at intermediate distances (2 Å to 10 Å)? interpolate!

$$f(r_{ij}) = \sqrt{r_{ij}^2 + a_i a_j \exp\left[-\frac{r_{ij}^2}{4a_i a_j}\right]}$$
$$\Delta G_{\text{ele}} = -\frac{1}{2} \left(1 - \frac{1}{\varepsilon}\right) \cdot \sum_{i,j} \frac{q_i \cdot q_j}{f(r_{ij})}$$

Generalized Born model (GB)

Born's equation holds for a charged particle in contact with solvent

problem 2 – many charges are buried deeply inside the protein, far from the solvent!

 \rightarrow solvation free energy may be overestimated heavily

possible solution – scale up a_i in a reasonable way!

the most important task when using the GB method - to use/calculate reasonable radii a_i

How to get the radii in GB

approximate interaction energy of a charge q_i in the protein interior with the solvent:

$$\Delta G^i_{\mathsf{ele}} = -rac{1}{8\pi} \left(1-rac{1}{arepsilon_W}
ight) \int_{\mathsf{ext}} rac{q_i^2}{r^4} \, \mathsf{d} V$$

integration runs over the 'exterior' of the protein

comparing with the Born formula, we find

$$\frac{1}{a_i} = \frac{1}{4\pi} \int_{\text{ext}} \frac{1}{r^4} \,\mathrm{d}V$$

r – distance from the charge to the 'boundary' of the protein.



How to get the radii in GB

several GB models exist; generally, \int_{ext} transformed to \int_{int} **GB** molecular volume – with van der Waals radius α_i :

$$\frac{1}{a_i} = \frac{1}{\alpha_i} - \frac{1}{4\pi} \int_{\text{int}, r > \alpha_i} \frac{1}{r^4} \, \mathrm{d}V$$

- possibly longish calculation time

pairwise models – the interior \approx union of atomic spheres

$$\frac{1}{a_i} = \frac{1}{\alpha_i} - \sum_{j \neq i} \frac{1}{4\pi} \int_{\text{sphere } j} \frac{1}{r^4} \, \mathrm{d}V$$

- this is insufficient because of partial overlap / void places

How to get the radii in GB

several GB models exist; generally, \int_{ext} transformed to \int_{int} **GB** molecular volume – with van der Waals radius α_i :

$$\frac{1}{a_i} = \frac{1}{\alpha_i} - \frac{1}{4\pi} \int_{\text{int}, r > \alpha_i} \frac{1}{r^4} \, \mathrm{d}V$$

- possibly longish calculation time

■ pairwise models – the interior ≈ union of atomic spheres empirical formula may be used instead:

$$\frac{1}{a_i} = \frac{1}{\lambda \cdot R_{\text{vdW},i}} - P_1 \frac{1}{R_{\text{vdW},i}^2} - \sum_j^{\text{bond}} \frac{P_2 V_j}{r_{ij}^4} - \sum_j^{\text{angle}} \frac{P_3 V_j}{r_{ij}^4}$$
$$- \sum_j^{\text{nonbond}} \frac{P_4 V_j}{r_{ij}^4} \cdot \text{CCF}(P_5, r_{ij})$$

MM-PBSA

- another application of implicit solvent models
- free energies of binding of ligands to biomolecules
- post-processing approach to evaluate free energies
- a normal MD simulation is run,

and free energies are computed a posteriori

binding free energy obtained component-wise with various methods solvation free energy – with Poisson–Boltzmann or so non-polar contribution – SASA-dependent terms configurational entropy – normal-mode analysis

very approximative, yet may still give results of good quality