Non-bonded interactions Continuum solvation models

Marcus Elstner and Tomáš Kubař

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Continuum electrostatics methods

Situation up to now

- molecules in an explicit solvent
- all interactions obviously involved
- polarizability / permittivity of the solvent considered implicitly
- for instance, solvation free energy involved implicitly
 - if desired, may be evaluated with special methods

Continuum electrostatics methods

Example – polypeptide in the α -helix and β -sheet conformations. The free energy difference of the two structures is given by

- the difference of internal energies / enthalpies
- the entropic contributions above all vibrational entropy

the difference of free energies of solvation

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 $\alpha\text{-helix:}$ much larger dipole moment than $\beta\text{-sheet}$

- $\rightarrow \alpha$ -helix is better solvated in a polar medium (H₂O)
- \rightarrow crucial effect of solvation on the equilibrium between conformations of solvated peptide

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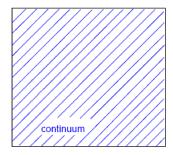
- $\rightarrow \alpha$ -helix is better solvated in a polar medium (H₂O)
- \rightarrow crucial effect of solvation on the equilibrium between conformations of solvated peptide

Motivation: the amount of solvent becomes excessive easily, so maybe meaningful – abandon explicit solvent, apply implicit model

Continuum electrostatics methods

Solvation free energy: $\Delta G_{solv} = \Delta G_{cav} + \Delta G_{vdW} + \Delta G_{ele}$

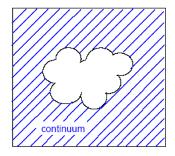
- A cavity in the solvent is formed
 - rearrangement of the solvent molecules
 - ΔG_{cav} : decrease of S and loss of solvent–solvent interactions
- solute-solvent interaction van der Waals and electrostatic



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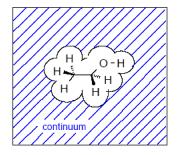
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Solvent-accessible surface area

SASA – important concept

- solvent-exposed surface of molecule as a solid body
- reasonable approx.: ΔG_{cav} and ΔG_{vdW} proportional to SASA.
- total surface composed from surfaces of individual atoms S_i

• Then:
$$\Delta G_{cav} + \Delta G_{vdW} = \sum_i c_i \cdot S_i$$

 alternative: obtain SASA by rolling a ball of a certain diameter (typically 2.8 Å to mimic H₂O) on the molecular surface

Solvent-accessible surface area

When does it work?

- if the electrostatic effect of the surrounding solvent dominates (shielding of solvent-exposed charged side chains of proteins)
- not if there is specific solute-solvent interaction (like hydrogen bonding)
- Difficult example: dynamics of small peptides dissolved in water
 - competition between various hydrogen-bonding patterns

Continuum electrostatics methods

Big question: how to calculate ΔG_{ele} ?

often used is the term "reaction field"

$$\Delta G_{
m ele} = q \cdot \Phi_{
m rf}(ec{r})$$

for moving the cavity with the solute from vacuo to the solvent

Born and Onsager models

Born: the work to bring charge q from vacuo into spherical cavity of radius a in solvent with dielectric constant ε :

$$\Delta G_{\mathsf{ele}} = -rac{q^2}{2a}\left(1-rac{1}{arepsilon}
ight)$$

 $\varepsilon:$ 1 for vacuo (thus $\Delta \textit{G}_{ele}=$ 0), 80 for water, 2 to 20 for protein

Onsager and Kirkwood: model for dipole μ in cavity

$$\begin{split} \Phi_{\mathsf{rf}} &=& \frac{2(\varepsilon-1)}{2\varepsilon+1} \cdot \frac{1}{a^3} \cdot \mu \\ \Delta G_{\mathsf{ele}} &=& -\frac{1}{2} \Phi_{\mathsf{rf}} \cdot \mu \end{split}$$

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Born and Onsager models

- simple models
- implemented in many standard programs
- quite uneralistis approximations even for small molecules

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Extensions:

- polarizable continuum model (PCM) arbitrary surfaces constructed with the use of vdW radii of individual atoms
- conductor-like screening models (COSMO) polarization of the dielectric (insulating) solvent derived from scaled-conductor approximation.

Poisson–Boltzmann equation (PBE)

For big molecules, the simple models may be too simple and inefficient at the same time :-(

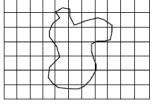
other approximations - starting from Poisson's equation

 $\nabla \varepsilon \nabla \Phi = -4\pi \rho$

given – charge distribution ρ and dielectric constant ε to be found – potential Φ

possibility to solve:

 discretize on a 3D grid, use finite differences calc. Φ on every grid point iteratively



lons in the solvent

ions are very important – counterions compensate charged solute, or salt mimicks physiologic conditions

the position of ions depends on the potential:

$$\rho_{\text{ions}} = \sum_{i} q_{i} \cdot c_{i} \cdot \exp\left[-\frac{q_{i} \cdot \Phi(r)}{k_{\text{B}}T}\right]$$

or: anions like to be where $\Phi>0,$ and cations like $\Phi<0$

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an additional term appears in Poisson's equation: linearized Poisson-Boltzmann equation at low ionic strength:

$$abla arepsilon
abla
abla \Phi = -4\pi
ho + arepsilon \cdot \kappa^2 \cdot \Phi(r)$$

with the Debye–Hückel parameter $\kappa^2 = \frac{8\pi q^2 I}{\varepsilon \cdot k_{\rm B} T}$ (ionic strength $I = \frac{1}{2} \sum_i c_i z_i^2$, c_i concentration, z_i charge of ion i)

lons in the solvent – PBE

 charge distribution on the protein polarizes the dielectric outside ("solvent") → screening of any solvent-exposed charges of the protein effectively, charges pointing into the solvent will vanish nearly
 solvent ions will distribute to make the overall charge distribution more uniform if a negative charge points into the solvent, a cation will be located close to it

The solvent around a protein should always be taken into account.

PBE – not efficient enough to be calculated in every MD step (approximations are necessary)

Generalized Born model (GB)

idea - use the simple Born equation for MM atomic charges

$$\Delta G^1_{\mathsf{ele}} = -\left(1-rac{1}{arepsilon}
ight)\sum_i rac{q_i^2}{2 oldsymbol{a}_i}$$

the interaction of individual charges changes in solution

$$E_{\text{ele}} = \frac{1}{2} \sum_{i \neq j} \frac{1}{\varepsilon} \frac{q_i \cdot q_j}{r_{ij}} =$$
$$= \frac{1}{2} \sum_{i \neq j} \frac{q_i \cdot q_j}{r_{ij}} - \frac{1}{2} \left(1 - \frac{1}{\varepsilon}\right) \sum_{i \neq j} \frac{q_i \cdot q_j}{r_{ij}}$$

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giving another contribution to solvation free energy

$$\Delta G_{\mathsf{ele}}^2 = -rac{1}{2}\left(1-rac{1}{arepsilon}
ight)\sum_{i
eq j}rac{q_i\cdot q_j}{r_{ij}}$$

solvation free energy $= \Delta \textit{G}_{ele}^1 + \Delta \textit{G}_{ele}^2$

Generalized Born model (GB)

problem 1 - Born's formula holds

for interaction of charges located in spherical cavities (with radii a_i)

- only valid for charged bodies of general shapes if $r_{ij} \gg a_i + a_j$
- two extreme cases are covered:

$$E = \begin{cases} \frac{q_i^2}{a_i}, & \text{if } i = j \text{ (`self-interaction, i.e. solvation energy)} \\ \frac{a_i}{q_i \cdot q_j}, & \text{if } i \neq j \text{ and } r_{ij} \to \infty \end{cases}$$

what to do at intermediate distances (2 Å to 10 Å)?

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what to do at intermediate distances (2 Å to 10 Å)? interpolate!

$$f(r_{ij}) = \sqrt{r_{ij}^2 + a_i a_j \exp\left[-\frac{r_{ij}^2}{4a_i a_j}\right]}$$
$$\Delta G_{\text{ele}} = -\frac{1}{2} \left(1 - \frac{1}{\varepsilon}\right) \cdot \sum_{i,j} \frac{q_i \cdot q_j}{f(r_{ij})}$$

Generalized Born model (GB)

Born's equation holds for a charged particle in contact with solvent

problem 2 – many charges are buried deeply inside the protein, far from the solvent!

 \rightarrow solvation free energy may be overestimated heavily

possible solution – scale up a_i in a reasonable way!

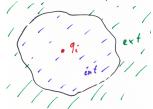
the most important task when using the GB method – to use/calculate reasonable radii *a_i*

How to get the radii in GB

approximate interaction energy of a charge q_i in the protein interior with the solvent:

$$\Delta G^i_{\mathsf{ele}} = -rac{1}{8\pi} \left(1-rac{1}{arepsilon_W}
ight) \int_{\mathsf{ext}} rac{q_i^2}{r^4} \, \mathsf{d} V$$

integration runs over the 'exterior' of the protein



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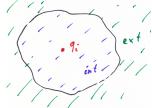
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comparing with the Born formula, we find

$$\frac{1}{a_i} = \frac{1}{4\pi} \int_{\text{ext}} \frac{1}{r^4} \,\mathrm{d}V$$

r – distance from the charge to the 'boundary' of the protein.



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How to get the radii in GB

several GB models exist; generally, $\int_{\rm ext}$ transformed to $\int_{\rm int}$

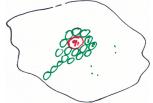
GB molecular volume – with van der Waals radius α_i :

$$\frac{1}{a_i} = \frac{1}{\alpha_i} - \frac{1}{4\pi} \int_{\text{int}, r > \alpha_i} \frac{1}{r^4} \, \mathrm{d}V$$

- possibly longish calculation time

pairwise models – the interior \approx union of atomic spheres

$$\frac{1}{a_i} = \frac{1}{\alpha_i} - \sum_{i \neq i} \frac{1}{4\pi} \int_{\text{sphere } j} \frac{1}{r^4} \, \mathrm{d} V$$



How to get the radii in GB

several GB models exist; generally, \int_{ext} transformed to \int_{int} **GB** molecular volume – with van der Waals radius α_i :

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■ pairwise models – the interior ≈ union of atomic spheres this is insufficient because of partial overlap / void places empirical formula may be used instead:

$$a_i^{-1} = \frac{1}{\lambda \cdot R_{\text{vdW},i}} - P_1 \frac{1}{R_{\text{vdW},i}^2} - \sum_j^{\text{bond}} \frac{P_2 V_j}{r_{ij}^4} - \sum_j^{\text{angle}} \frac{P_3 V_j}{r_{ij}^4}$$
$$- \sum_j^{\text{nonbond}} \frac{P_4 V_j}{r_{ij}^4} \cdot \text{CCF}(P_5, r_{ij})$$

MM-PBSA

- another application of implicit solvent models
- free energies of binding of ligands to biomolecules
- post-processing approach to evaluate free energies
- a normal MD simulation is run, and free anarrise are computed as

and free energies are computed a posteriori

binding free energy obtained component-wise with various methods solvation free energy – with Poisson–Boltzmann or so non-polar contribution – SASA-dependent terms configurational entropy – normal-mode analysis

very approximative, yet may still give results of good quality