

Various topics

Coarse graining; hard bodies; Monte Carlo techniques

Marcus Elstner and Tomáš Kubař

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United-atom force fields

- early biomolecular FF (e.g. Weiner84), popular in the 1990's
- hydrogen atoms considered as **condensed** to the heavy atom
- mass and charge represent such a group of atoms as a whole
- number of atoms reduced considerably relative to **all-atom** FF

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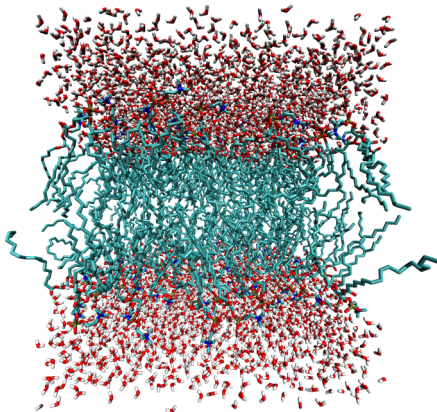
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- mass and charge represent such a group of atoms as a whole
- number of atoms reduced considerably relative to **all-atom** FF
- good for non-polar C–H bonds – so CH₃ is one united atom
- polar O–H group by a single 'atom' – too crude
 - only non-polar hydrogens usually condensed with heavy

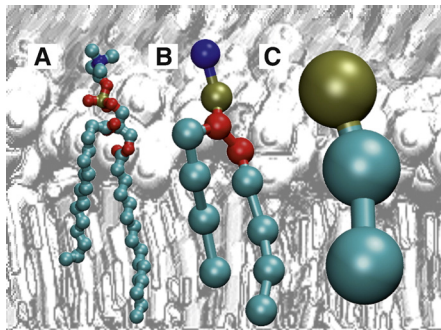
United-atom force fields

still sometimes used e.g. for lipids – each CH_2 is a united atom



(simulation of a DOPC bilayer in water – Berger FF for the lipid)

United-atom and coarse-grained force fields



(A) united-atom, (B) specific and (C) generic coarse-grained

from Marrink et al., Biochim. Biophys. Acta 2009

Coarse-grained models

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Fewer inter-particle interactions → reduced computational expense

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Fewer inter-particle interactions → reduced computational expense

The necessary parameters – often obtained by fitting to all-atom force fields

Coarse-grained models

Every bead usually represents several atoms,
and a molecule is composed of several beads

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– e.g. secondary structure of proteins is fixed with Martini FF

Also, hydrogen bonding cannot be described with beads!

solution – compensation with Lennard-Jones contributions

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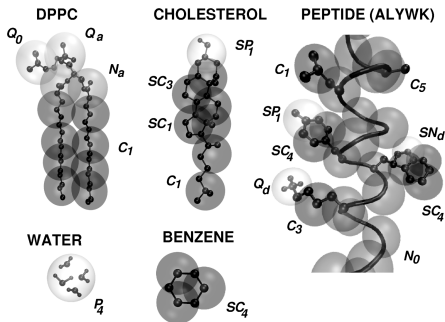
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solution – compensation with Lennard-Jones contributions

Especially useful for large-scale conformational transitions involving exceedingly large molecular systems, excessive time scales, or both

Martini force field

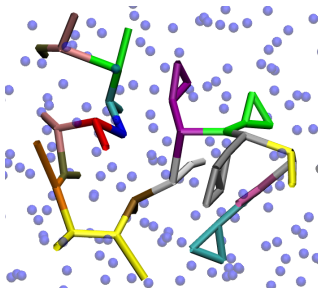
mapping of beads onto molecular fragments with Martini FF



- 3 to 4 heavy atoms compose one bead ('4-to-1 mapping')
- mass of beads – 72 u ($= 4 \text{ H}_2\text{O}$), or 45 u in ring structures

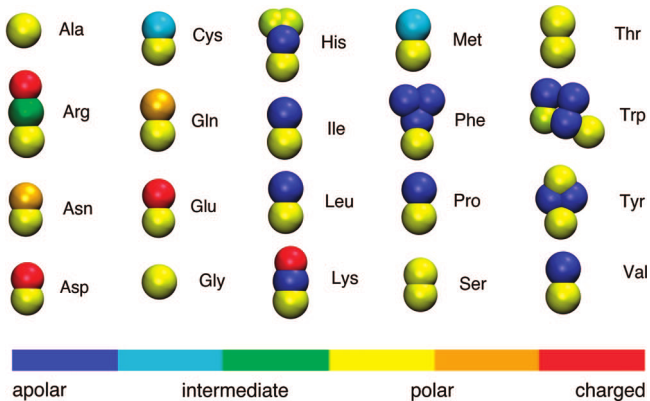
Martini force field

a solvated peptide with Martini FF



Martini force field

the amino acids:



Acceleration of the simulation

Why does a coarse-grained simulation run faster?

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 - 25 fs with Martini (i.e. 100 fs effectively, see below)

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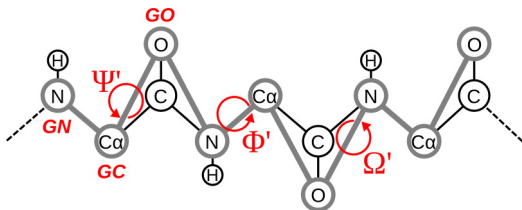
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“... length and time scales that are 2 to 3 orders of magnitude larger compared to atomistic simulations, providing a bridge between the atomistic and the mesoscopic scale.”

Coarse-grained models

SIRAH force field

- somewhat less coarse-grained, closer to united-atom
- representation of backbone dihedral angles retained















from Pantano et al., J. Chem. Theory. Comput. 2015

Coarse-grained models

SIRAH force field

- less coarse-grained → possibly improved transferability
- explicit solvent, long-range electrostatics (no cut-off)

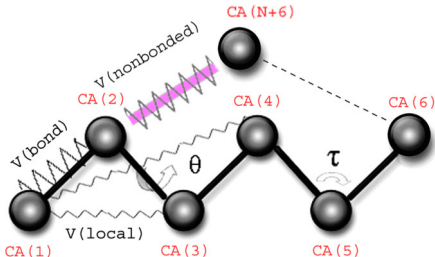
FG	CG	SIRAH name	q (e)	σ (nm)	ϵ (kJ/mol)	FG	CG	SIRAH name	q (e)	σ (nm)	ϵ (kJ/mol)
G 		1: GC	0,10	0,40	0,55	W 		4: BCG	0	0,35	1,70
		2: GN	0,125	0,40	0,55			5: BNE	-0,10	0,35	0,10
		3: GO	-0,225	0,40	0,55			6: BPE	0,10	0,35	0,01
S 		4: BOG	-0,20	0,41	0,35			7: BCZ	0	0,35	1,70
		5: BPG	0,20	0,40	0,01	E 		8: BCE	0	0,35	1,70
Na ⁺ and 6 water molecules 		1: NaW	1,00	0,58	0,55			4: BCD	-0,30	0,40	0,35
								5: BOE1	-0,35	0,45	0,55
WT4 11 water molecules 								6: BOE2	-0,35	0,45	0,55
								1: WN1	-0,41	0,42	0,55
								2: WN2	-0,41	0,42	0,55
								3: WP1	0,41	0,42	0,55
								4: WP2	0,41	0,42	0,55

- illustration – different compromises may be made

Coarse-grained models

VAMM force field for proteins

- every amino acid represented by a single bead at C_α



- more coarse-grained than Martini

from Korkut & Hendrickson 2009

MD simulation of hard bodies

first MD simulation of a system in the condensed phase

- used the model of **hard spheres**
(Alder & Wainwright, J. Chem. Phys. 1957)
- first step from the ideal gas towards realistic molecules
- valuable tool in statistical thermodynamics
→ equations of state and virial expansions

The hard-sphere potential

- pairwise potential
- potential energy of a system of two hard spheres with radius R is zero for distances larger than the diameter of the spheres is infinity for shorter distances, when the spheres overlap:

$$V(r) = \begin{cases} 0 & \text{if } r > 2R \\ +\infty & \text{otherwise} \end{cases}$$

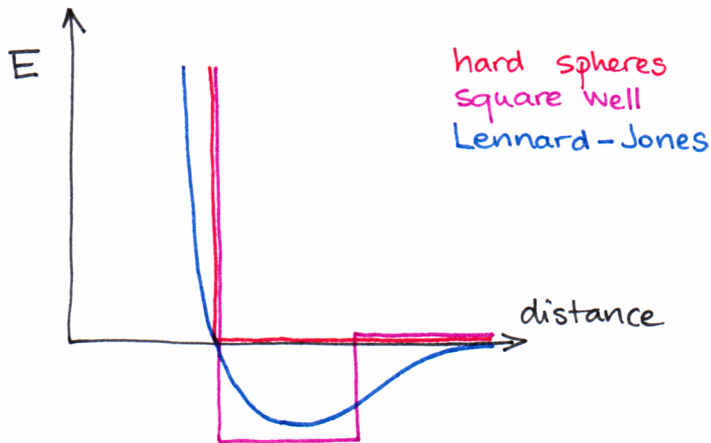
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- is **discontinuous** → not differentiable
- different from potentials typically used in biomolecular simulation

The hard-sphere potential



The square-well potential

a more realistic description preserving the simplicity of the model?

square well model

- region of negative potential energy (attractive interaction)
starting at the contact distance $2R$
- goes in the direction of the Lennard-Jones potential,
which describes nonpolar fluids very well

Hard convex bodies

- another extension used in statistical thermodynamics
- potential energy function is discontinuous, still:
zero if the bodies do not intersect; infinity if they do

Hard convex bodies

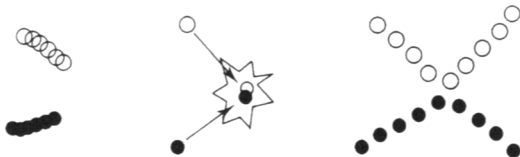
- another extension used in statistical thermodynamics
- potential energy function is discontinuous, still:
zero if the bodies do not intersect; infinity if they do
- enhancement – the bodies are not spherical anymore,
but rather ellipsoidal or polyhedral
- may describe e.g. diatomic molecules better than hard sphere

Simulation protocol

propagation of Newton's EOM with e.g. Verlet integrator
– continuous and smooth potential required
otherwise – sudden 'jumps' in forces lead to unstable simulations,
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reprinted from Leach, Molecular Modelling

Simulation protocol

Hard spheres cannot be simulated with a usual integrator

- explosions caused by sudden clashes of atoms would occur (similar to those in usual MD simulations with too large Δt)

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What would a simulation of hard spheres with Verlet look like?

There are no forces in any initial configuration,
and so the spheres move with their initial velocities
until, all of a sudden, two spheres start to overlap.

The energy and forces are infinite, and the simulation crashes.

Simulation protocol

The protocol has to be adjusted to the discontinuous potential

- event-driven protocol

The spheres move along straight lines between collisions,
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- 1 Identify the next pair of spheres to collide,
and calculate when this collision will occur
- 2 Calculate the positions of all spheres at the collision time –
conservation of linear momentum and of kinetic energy
- 3 Determine the new velocities of the two spheres after collision
- 4 Repeat from start

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No further approximations are involved in this protocol

→ simulation will be **exact** within the model of hard spheres

Note: With continuous potentials, we **had to** make approximations, like a stepwise integration of the eqns of motion

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Potential energy – constant (zero) throughout the simulation

Conservation of total energy → conservation of kinetic energy

→ temperature is constant in any hard-spheres simulation

Monte Carlo simulation

The main objective of molecular dynamics –
mostly not to study how the molecular system evolves in time,
rather to generate configurations of the system
(sampling \rightarrow calculation of thermodynamic quantities)
MD is not the only possibility to do this ...

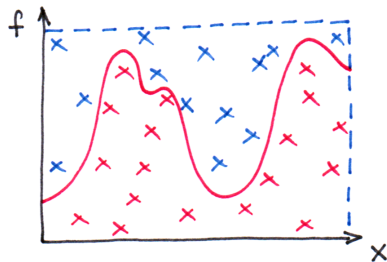
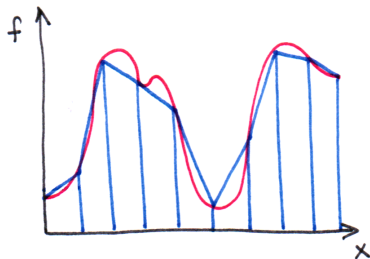
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Another possibility – Monte Carlo methods (MC),
which involve random number generators Actually, first
computer simulations of molecular systems were MC
(Metropolis et al., J. Chem. Phys. 1953)

Monte Carlo integration

A major goal of molecular simulation – calculation
of thermodynamic properties – integration (formally)
Can we use a method based on randomness for integration?



Monte Carlo integration

Possibility – trapezium rule –

comes into trouble for functions of many variables
(and there are many variables in molecular systems)

Alternatively – generate N points randomly
and count the points (n) under the curve.

Then, the area under the curve relative to the rectangle is $\approx n/N$.

Apply the Monte Carlo idea to calculate π as follows:

Generate pairs of random number between 0 and 1 (x, y).

Count the pairs for which $x^2 + y^2 < 1$, i.e. the point (x, y)
lies within the circle centered at (0,0) with a radius of 1.

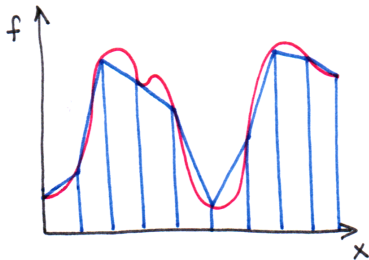
The ratio of this number to the total number of pairs approaches $\pi/4$.

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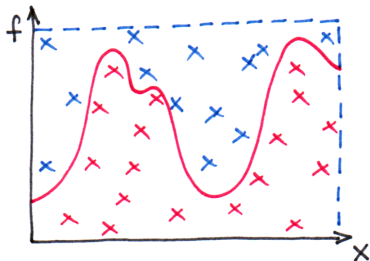
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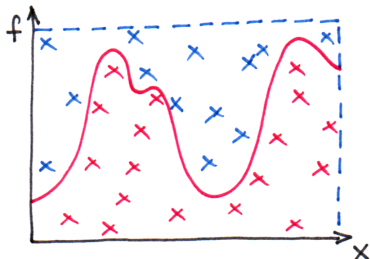


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Groundbreaking idea (Metropolis):

Generate the configurations with the **right probability**,
creating the correct thermodynamic (e.g. canonical) **ensemble**

Such **importance sampling** will make it trivial to average
thermodynamics quantities over the generated configurations

Metropolis' method

Typical MC simulation of a molecular system

- a sequence of configurations is generated in an iterative way
- in every iteration, one configuration is produced.

Usually:

- 1 A **trial** configuration is constructed from the current one by randomly shifting one randomly chosen particle (atom).

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Usually:

- 1 A **trial** configuration is constructed from the current one by randomly shifting one randomly chosen particle (atom).
- 2 It is tested if this configuration shall be **accepted or not**.
For this, potential energy of the entire system is calculated.
(possible optimization – only small part of the system changes,
→ only a small fraction of the interactions changes)

Metropolis' method

Trial set of coordinates is calculated with random $\xi_{x,z,y} \in (0, 1)$:

$$x_{\text{trial}} = x + (2\xi_x - 1) \cdot \delta r$$

$$y_{\text{trial}} = y + (2\xi_y - 1) \cdot \delta r$$

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$$\mathcal{P} = \begin{cases} 1 & \text{if } U_{\text{trial}} < U \\ \exp \left[-\frac{U_{\text{trial}} - U}{k_B T} \right] & \text{otherwise} \end{cases}$$

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The trial configuration is **accepted** if $\mathcal{P} > \text{random } \zeta \in (0, 1)$ otherwise it is **discarded** and another trial is generated

Acceptance ratio

The percentage of accepted configurations (among all generated) governed by max. allowed displacement δr – adjustable parameter

- usually chosen so that $\frac{1}{3}$ to $\frac{1}{2}$ of all configs are accepted
- this was shown to lead to the most efficient sampling

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δr too small \rightarrow most configurations are accepted though,
but the configurations are very similar \rightarrow slow sampling

δr too large \rightarrow too many trial configurations are rejected

Often – δr adjusted in the course of the simulation

in order to reach a certain target acceptance ratio

Properties of MC

- generates a correct thermodynamic ensemble (canonical)
- involves **temperature** naturally
 - no additional thermostat necessary
 - difference from MD
- no kinetic information (velocities, E_{kin})

MC protocol – variations

Possible modifications to the algorithm:

- move the atoms sequentially, in a preset order, instead of selecting one randomly – one fewer random number needed
- move several atoms at once, instead of a single atom
 - very efficient sampling of config space (with appropriate δr)

Generators of pseudorandom numbers

Several random numbers in every iteration have to be obtained
and a large number of iterations is needed
→ reliable and efficient source of random numbers needed.

Most convenient – ‘calculate’ random numbers in some way
paradoxical requirement (computers are deterministic)

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There are ways to generate sequences of **pseudorandom numbers**
not actually random, but still independent enough of each other,
with right statistical properties → useful for MC

Linear congruential generators

- most commonly used generators
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value $\in (0, 1)$ is obtained by dividing ξ_{i+1} by the modulus m

Linear congruential generators

Very important – choose appropriate values of a , b and m

Then, the generator will produce all possible values $0, \dots, m - 1$
and will start to repeat the sequence only after m numbers.

Otherwise – the sequence starts to repeat itself much earlier,
and the randomness is severely limited.

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Disadvantage – if we generate points in an N -dimensional space,
these are not distributed uniformly in the space,
but rather they lie on at most $\sqrt[N]{m}$ $(N - 1)$ -dimensional planes
(i.e. on straight lines if we have a 2D space).

With really poor generators – much fewer than $\sqrt[N]{m}$ hyperplanes.

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With really poor generators – much fewer than $\sqrt[N]{m}$ hyperplanes.

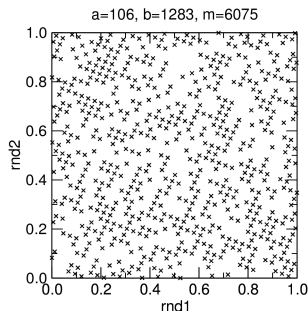
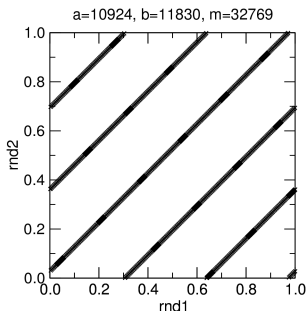
An example is RANDU: ξ_0 is odd and $\xi_{i+1} = 65539 \cdot \xi_i \bmod 2^{31}$.

All generated values are odd, the period is only 2^{29} ,

and the points $(\xi_i, \xi_{i+1}, \xi_{i+2})$ cumulate on as few as 15 planes in space.

Linear congruential generators

A bad and a good generator of pseudorandom numbers.



Each point $(rnd1, rnd2)$ is a pair of consecutive numbers from LCG

Generators of higher quality

Still, LCG are often used in MC simulations
because of extreme simplicity and computational efficiency.

Higher-quality pseudorandom number generators:

linear feedback shift register generators

- uses several bits from current number to generate new ones
- does not cumulate the generated numbers on hyperplanes

Mersenne twister

- current state of the art among generators
- extremely long period of $2^{19937} - 1$
- no cumulation of numbers on hyperplanes up to 623 dim.
- even suitable for cryptographic applications

Alternative generators of random numbers

In Unix-like operating systems (with Linux being the first),
 /dev/random (or /dev/urandom) is a special file
 that serves as a random or pseudorandom number generator.
It accesses environmental noise collected from device drivers etc.

from Wikipedia

Monte Carlo simulation of molecules

Easiest implementation – system of monoatomic molecules
(translational degrees of freedom only)

Polyatomic molecules – more complex situation,
most difficult if there is large conformational flexibility

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→ overlap of atoms → energy grows steeply

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Rigid molecules – still quite easy to simulate with MC

– orientation in space being varied beside position in space

– rotation along an axis x , y or z by randomly chosen angle

Monte Carlo simulation of molecules

Particularly rich area of application of MC
– macromolecular chemistry

Monte Carlo simulation of polymers

Many approximative polymer models are suitable for MC simulation
Convenient – a chain of monomer units,
which are elementary particles (no further internal structure)

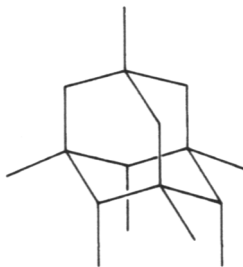
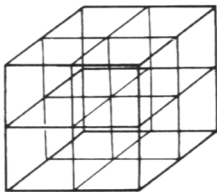
Monte Carlo simulation of polymers

Many approximative polymer models are suitable for MC simulation

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Lattice models – very simple and useful for efficient studies

- monomer units connected with a bond can occupy neighboring lattice points in a cubic or tetrahedral lattice

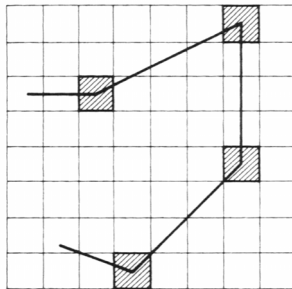
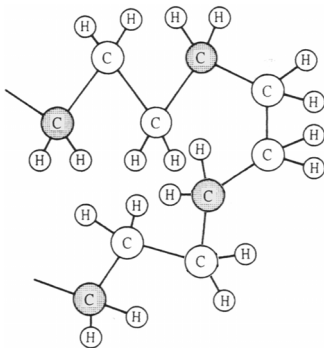


Monte Carlo simulation of polymers

Usually – very simple expressions for potential energy
(simplicity of the model + requirement of efficiency)

More realistic and complex – **bond fluctuation** model

- lattice is finer-grained compared to the bond length
- ‘effective’ bonds are not constrained to the edges of lattice



Monte Carlo simulation of polymers

Simplest type of simulation – **random walk**

- the chain grows in a random direction until the desired length
- first implementation – excluded volume of previous segments is not considered, so the chain is free to cross itself

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Various structural properties can be evaluated

by averaging the results over many growing ‘simulations’.

Quantities of interest: end-to-end distance R_n , radius of gyration s_n

$$\begin{aligned}\langle R_n^2 \rangle_0 &= n \cdot l^2 \\ \langle s^2 \rangle_0 &= \langle R_n^2 \rangle / 6\end{aligned}$$

for a chain composed of n bonds with length l

Monte Carlo simulation of polymers

Excluded volume not described – may seem to be crude,
but this may not be a problem

Monte Carlo simulation of polymers

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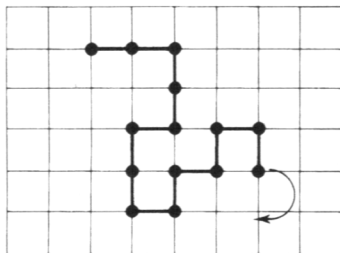
theta state (ϑ state) of a polymer

- excluded volume and attractive interactions cancel exactly
(also, the second virial coefficient vanishes)
- results derived with simple random walk are actually valid
(often designated with the subscript '0')

Monte Carlo simulation of polymers

How to take the excluded volume into account?

- do not allowing the chain to extend to already occupied points
- self-avoiding walk



Monte Carlo simulation of polymers

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SAW was used to generate all possible configurations
of a polymer of given length on a given lattice

→ partition function → all thermodynamic properties

‘potential energy’ – simple interaction model for nearby monomers
also – copolymers with two different types of monomer units

particular attention – structural properties – end-to-end distance:

$$\langle R_n^2 \rangle \approx n^{1.18} \cdot l^2 \quad \text{for } n \rightarrow \infty$$

Monte Carlo simulation of polymers

to modify the configuration with MC – nearly impossible
because no free space (espec. for densely packed polymers)

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slithering snake model – a trick to avoid the problem:

1. choose one end of the polymer chain randomly as the head
2. make MC attempt to connect a new monomer unit to head
3. on success, then remove one monomer from the other end
4. repeat

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How to improve the lattice models? ... cancel the lattice

- ‘**continuous**’ **polymer models** – string of connected **beads**
- freely connected, with a spherically symmetric potential (LJ)
- do not generally correspond to monomer units
- links (‘bonds’) either fixed or with a harmonic potential

Monte Carlo simulation of polymers

most unrealistic property – continuous variation of link angles

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freely rotating chain model – link angles are fixed

- free rotation about the links ('dihedral angles') allowed
- this changes the overall structure of the polymer chain!

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most unrealistic property – continuous variation of link angles

freely rotating chain model – link angles are fixed

- free rotation about the links ('dihedral angles') allowed
- this changes the overall structure of the polymer chain!
- the **extension** of a chain with interlink angle φ ,
with respect to the freely connected chain:

$$C_n = \frac{\langle R_n^2 \rangle}{n \cdot l^2} \quad \rightarrow \quad C_\infty = \frac{1 - \cos \varphi}{1 + \cos \varphi}$$

so, for a tetrahedral bond angle $\varphi = 109^\circ$: $C_\infty \approx 2$

Monte Carlo simulation of polymers

rotational isomeric state model (Flory, 1969)

- every link is always in one of defined rotational states
- these states, dihedral angles, are minima of pot. energy
- e.g. trans, gauche(+) and gauche(−) in polyalkane chain

Monte Carlo simulation of polymers

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- every link is always in one of defined rotational states
- these states, dihedral angles, are minima of pot. energy
- e.g. trans, gauche(+) and gauche(−) in polyalkane chain
- conformation-dependent properties described with matrices
- best known approximative description of polymer chains
- combined with MC → wide range of properties
 - conformations of chain are generated with probability distributions corresponding to their statistical weights, which are a component of the model (in a matrix form)

Monte Carlo simulation of polymers

rotational isomeric state model

matrix of statistical weights for an example of polyalkane chain:

$$U \equiv \begin{pmatrix} u_{tt} & u_{tg^+} & u_{tg^-} \\ u_{g^+t} & u_{g^+g^+} & u_{g^+g^-} \\ u_{g^-t} & u_{g^-g^+} & u_{g^-g^-} \end{pmatrix} = \begin{pmatrix} 1.00 & 0.54 & 0.54 \\ 1.00 & 0.54 & 0.05 \\ 1.00 & 0.05 & 0.54 \end{pmatrix}$$

u_{ab} – statistical weight of dihedral state b
following a link in the dihedral state a

Monte Carlo simulation of polymers

rotational isomeric state model

Starting on one end of the chain, a conformation is generated by calculating the dihedral angles sequentially, until the whole chain is done.

The probability of each dihedral angle is determined with MC using the a priori probabilities of the dihedral states and the state of the previous dihedral angle.

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In a typical study, a large number of such chain will be grown, and the properties of interest will be calculated and averaged. Estimated can be pair correlation functions, scattering functions and force–elongation profiles.